

Fig. Q. 16(a)

- (1) For $\Delta < \pi/2\omega_M$, sketch the Fourier transform of $x_p(t)$ and $y(t)$
 - (2) For $\Delta < \pi/2\omega_M$, determine a system that will recover $x(t)$ from $x_p(t)$.
 - (3) For $\Delta < \pi/2\omega_M$, determine a system that will recover $x(t)$ from $y(t)$.
 - (4) What is the maximum value of Δ in relation to ω_M for which $x(t)$ can be recovered from either $x_p(t)$ or $y(t)$.
- (ii) Using figure 16(a)(i) determine $y(t)$ and sketch $Y(\omega)$ if $X(\omega)$ is given by figure 16(a)(ii). Assume $\omega_c < \omega_0$. $X(\omega)$ (4)

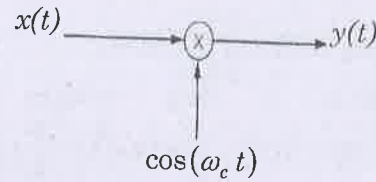


Figure 16(a)(i)

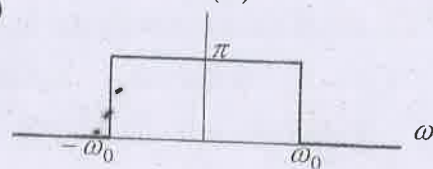
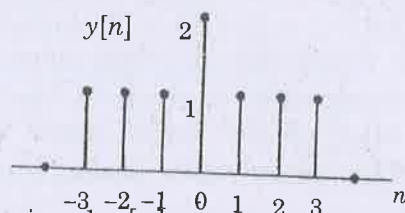


Figure 16(a)(ii)

Or

- (b) (i) (1) Suppose that the signal $e^{j\omega t}$ is applied as the excitation to a linear, time-invariant system that has an impulse response $h(t)$. By using the convolution integral, show that the resulting output is $H(\omega) e^{j\omega t}$, where $H(\omega) = \int_{-\infty}^{\infty} h(\tau) e^{j\omega\tau} d\tau$.
- (2) Assume that the system is characterized by a first-order differential equation $\frac{dy(t)}{dt} + \alpha y(t) = x(t)$.
If $x(t) = e^{j\omega t}$ for all t , then $y(t) = H(\omega) e^{j\omega t}$ for all t . By substituting into the differential equation, determine $H(\omega)$. (8)

- (ii) Consider the signal $y[n]$.



- (1) Find a signal $x[n]$ such that Even $\{x[n]\} = y[n]$ for $n \geq 0$, and Odd $\{x[n]\} = y[n]$ for $n < 0$.
- (2) Suppose the Even $\{w[n]\} = y[n]$ for all n . Also assume that $w[n] = 0$ for $n < 0$. Find $w[n]$.

Reg. No. :

Question Paper Code : 80112

B.E./B.Tech. DEGREE EXAMINATIONS, APRIL/MAY 2019.

Third Semester

Electronics and Communication Engineering

EC 8352 — SIGNALS AND SYSTEMS

(Common to Medical Electronics/B.E. Biomedical Engineering/Computer and Communication Engineering/Electronics and Telecommunication Engineering)

(Regulation 2017)

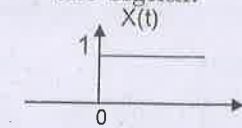
Time : Three hours

Maximum : 100 marks

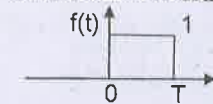
Answer ALL questions.

PART A — (10 × 2 = 20 marks)

1. Find the even and odd part of the signal.



2. Determine whether the given discrete time sequence is periodic or not. If the sequence is periodic, find the fundamental period. $x[n] = \cos\left(\frac{n}{8}\right) \cos\left(\frac{\pi n}{8}\right)$.
3. Find the Fourier series coefficients for the given signal.
 $x(t) = [1 + \cos(2\pi t)] \left[\sin\left(10\pi t + \frac{\pi}{6}\right) \right]$.
4. Find the Laplace transform of the given signal.



5. Check whether the given system is causal and stable. $h(t) = (e^{-4t}) u(t+10)$.
6. State Dirichlet's condition for Region of convergence.
7. Define Sampling theorem.
8. Write the relationship between DTFT and Z-transform.
9. Determine the Z-transforms of the following two signals. Note that the Z-transforms for both have the same algebraic expression and differ only in the ROC. $x_1[n] = \left(\frac{1}{2}\right)^n u[n]$ and $x_2[n] = -\left(\frac{1}{2}\right)^n u[-n-1]$.

10. Find the initial and final values of the function, $X(z) = \frac{1+z^{-1}}{1-0.25z^{-2}}$.

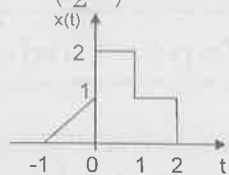
PART B — (5 × 13 = 65 marks)

11. (a) (i) Draw the waveforms represented by the following step functions,
 $\rightarrow f_1(t) = 2u(t-1)$ $\rightarrow f_2(t) = -2u(t-2)$
 $\rightarrow f(t) = f_1(t) + f_2(t)$ $\rightarrow f(t) = f_1(t) - f_2(t)$. (5)
- (ii) Determine the energy and power of the given signal $x(t) = t u(t)$. (4)
- (iii) Check whether the given system is linear or not $y(t) = x^2(t)$. (4)

Or

- (b) (i) A continuous time signal $x(t)$ is shown in figure below, Sketch and label each of the following signals.

$x(t-2)$, $x(2t+3)$, $x\left(\frac{3}{2}t\right)$, and $x(-t+1)$. (4)



- (ii) Determine the energy and power of the given signal. (4)

$x[n] = \cos\left[\frac{\pi}{4}n\right]$.

- (iii) Check whether the given system is Linear/nonlinear, Time Variant /Time Invariant, Causal/Non-causal $y[n] = x[n] - x[n-1]$. (5)

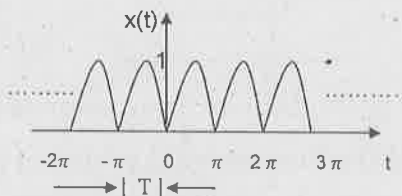
12. (a) Find the Fourier transform of each of the following signals and sketch the magnitude and phase as a function of frequency, including both positive and negative frequencies (13)

(i) $\delta(t-5)$

(ii) $e^{-at}u(t)$ a real, positive.

Or

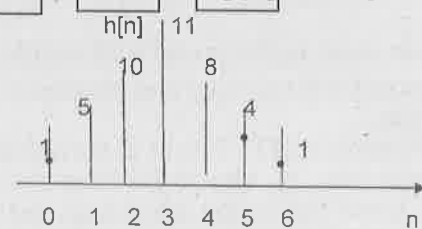
- (b) (i) Determine the Fourier Series representation of the given full wave rectifier. (8)



- (ii) List the properties of Laplace transform and write its ROC. (5)

13. (a) (i) Consider the cascade interconnection of three stage causal LTI system with impulse response $h_1[n]$, $h_2[n]$ and $h_3[n]$ as shown in figure below. The impulse response $h_2[n] = u[n] - u[n-2]$. The overall impulse response $h[n]$ is given in the figure below.

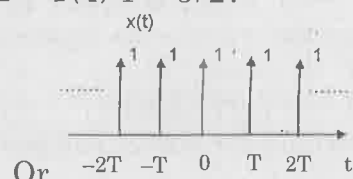
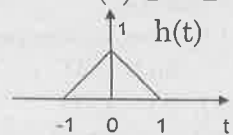
$x[n] \rightarrow h_1[n] \rightarrow h_2[n] \rightarrow h_3[n] \rightarrow y[n]$



Find the impulse response $h_1[n]$ and the response $y[n]$ of the overall system to the input $x[n] = \delta[n] - \delta[n-1]$. (9)

- (ii) Let $h(t)$ be a triangular pulse and let $x(t)$ be the impulse train. Determine and sketch $y(t)$ for the following values of T . (4)

(1) $T = 4$ (2) $T = 2$ (3) $T = 1$ (4) $T = 3/2$.



Or

- (b) (i) Find the convolution between $x[n]$ and $h[n]$, where $x[n] = (\alpha)^n u[n]$; $0 < \alpha < 1$ and $h[n] = u[n]$. (6)

- (ii) Find the convolution of $x(t)$ and $h(t)$ (7)

$x(t) = \begin{cases} 2 & \text{for } -2 \leq t \leq 2 \\ 0 & \text{otherwise} \end{cases}$ and $h(t) = \begin{cases} 4 & \text{for } 0 \leq t \leq 2 \\ 0 & \text{otherwise} \end{cases}$

14. (a) (i) Find the inverse Laplace transform of $\frac{s+4}{2s^2+5s+3}$; $Roc : Re\{s\} > -1$. (4)

- (ii) Consider the LTI system with impulse response $h[n] = (\alpha)^n u[n]$; $|\alpha| < 1$ and $x[n] = (\beta)^n u[n]$; $|\beta| < 1$. Find the response of the LTI system. (9)

Or

- (b) (i) Consider a discrete-time LTI system with impulse response $h[n] = \left[\frac{1}{2}\right]^n u[n]$. Use Fourier transform to determine the response

of the system to the input $x[n] = \left[\frac{3}{4}\right]^n u[n]$. (6)

- (ii) A difference equation of the system is given as, $y(n) - y(n-1) + \frac{1}{4}y(n-2) = x(n) + \frac{1}{4}x(n-1) - \frac{1}{8}x(n-2)$.

Determine the transfer function of the inverse system. Check whether the inverse system is causal and stable. (7)

15. (a) (i) Find the inverse Z-transform of $X(z) = \frac{1 - (1/2)z^{-1}}{1 + (3/4)z^{-1} + (1/8)z^{-2}}$; $|Z| > \frac{1}{2}$. (8)

- (ii) Compute discrete-time Fourier Transform of $x(n) = a^n$ for $0 \leq n \leq N-1$. (5)

Or

- (b) (i) Determine the Z-transform and ROC of the given sequence. (5)

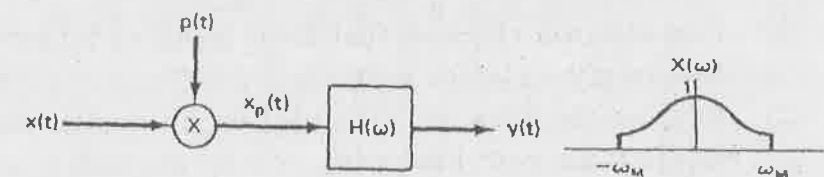
$x[n] = \left(\frac{-1}{3}\right)^n u[n] - \left(\frac{1}{2}\right)^n u[-n-1]$.

- (ii) Obtain the direct form I and direct form II realizations of the LTI system. (8)

$y(n) = -\frac{3}{8}y(n-1) + \frac{3}{32}y(n-2) + \frac{1}{64}y(n-3) + x(n) + 3x(n-1) + 2x(n-2)$.

PART C — (1 × 15 = 15 marks)

16. (a) (i) A system in which the sampling signal $p(t)$ is an impulse train with alternating sign is given in the figure 16(a). The Fourier transform $x(\omega)$ of the input signal are $x(t)$ and the Fourier transform $H(\omega)$ as indicated in the figure 16. (11)



15. (a) Let $y[n]=x[n]*h[n]$
 where $x[n]=\left(\frac{1}{3}\right)^n u[n]$ and
 $h[n]=\left(\frac{1}{5}\right)^n u[n]$

Find $y(z)$ by using the convolution property of z -transform and find $y[n]$ by taking the inverse transform of $y(z)$ using the partial fraction expansion method.

Or

- (b) A causal DT LTI system is described by the difference equation

$$y[n-2] - \frac{7}{10}y[n-1] + \frac{1}{10}y[n] = x[n]$$

Determine the system function $H(z)$. Also plot the pole-zero plot and determine whether the system is stable.

PART C — (1 × 15 = 15 marks)

16. (a) Given the impulse response of a discrete time LTI system

$$h[n] = \left[-2 \left(\frac{1}{3}\right)^n + 3 \left(\frac{1}{2}\right)^n \right] u[n]$$

- (i) Find the system function $H(z)$ of the system
 (ii) Find the difference equation representation of the system
 (iii) Find the step response of the system.

Or

- (b) The input output relationship of a discrete time system is given by

$$y[n] - \frac{1}{4}y[n-1] = x[n]. \text{ Find the response } y[n] \text{ if the Fourier transform of the input } x[n] \text{ is given as } X(e^{j\omega}) = \frac{1}{1 - \frac{1}{2}e^{-j\omega}}$$

Reg. No. :

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Question Paper Code : 25073

B.E./B.Tech. DEGREE EXAMINATION, NOVEMBER/DECEMBER 2018.

Third Semester

Electronics and Communication Engineering

EC 8352 — SIGNALS AND SYSTEMS

(Common to : Electronics and Telecommunication Engineering/ Medical Electronics/ Biomedical Engineering/ Computer and Communication Engineering)

(Regulations 2017)

Time : Three hours

Maximum : 100 marks

Answer ALL questions.

PART A — (10 × 2 = 20 marks)

1. Give the mathematical and graphical representations of a discrete time ramp sequence.
2. Evaluate the following integral

$$\int_{-1}^1 (2t^2 + 3) \delta(t) dt.$$
3. State Dirichlet's conditions.
4. If $X(j\Omega)$ is the Fourier transform of the signal $x(t)$, what is the Fourier transform of the signal $x(3t)$ in terms of $X(j\Omega)$?
5. If the system function $H(s) = 4 - \frac{3}{s+2}$; $\text{Re}(s) > -2$, find the impulse response $h(t)$.
6. Two systems with impulse response $h_1(t) = e^{-2t} u(t)$ and $h_2(t) = \delta(t-1)$ are connected in series. What is the overall impulse response $h(t)$ of the system?

7. A continuous time signal $x(t)$ has the following real Fourier transform :

$$X(j\Omega) = \begin{cases} 1, & |\Omega| \leq 10\pi \\ 0, & \text{otherwise} \end{cases}$$

Is $x(t)$ band limited? If so, find the Nyquist rate.

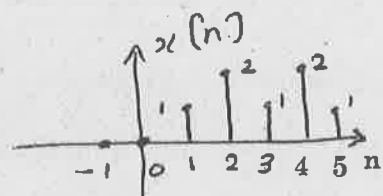
8. The DTFT of a discrete time signal $x(n)$ is given as $X(e^{j\omega}) = 2e^{2j\omega} + 3 + 4e^{-j\omega} - 2e^{-2j\omega}$. Find the time domain signal $x(n)$.

9. The input $x(n)$ and output $y(n)$ of a discrete time LTI system is given as $x(n) = \{1, 2, 3, 4\}$ and $y(n) = \{0, 1, 2, 3, 4\}$. Find the impulse response $h(n)$.

10. Given the system function $H(z) = \frac{z^{-1}}{z^{-2} + 2z^{-1} + 4}$. Find the difference equation representation of the system.

PART B — (5 × 13 = 65 marks)

11. (a) A discrete time signal $x(n]$ is shown below :



Plot the following signals :

- (i) $x[n-2]$ (2)
- (ii) $x[n+1]$ (2)
- (iii) $x[-n]$ (2)
- (iv) $x[-n+1]$ (2)
- (v) $x[2n]$ (2)
- (vi) $x[-2n+1]$ (3)

Or

(b) A continuous time system has the input-output relation given by $y(t) = tx(t-1)$

Determine whether the system is

- (i) Linear (3)
- (ii) Time-invariant (3)
- (iii) Stable (3)
- (iv) Memoryless (2)
- (v) Causal. (2)

12. (a) Find the Fourier transform of $x(t) = e^{-a|t|}$, $a > 0$ and sketch its corresponding magnitude spectrum.

Or

(b) Find the Laplace transform of $x(t) = e^{-a|t|}$, $a > 0$ and its associated ROC and indicate whether the Fourier transform $X(j\Omega)$ exists.

13. (a) Find the output $y(t)$ of the system

$$H(s) = \frac{1}{s+2} \quad \text{Re}\{s\} > -2$$

for the input $x(t) = e^{-3t} u(t)$.

Or

(b) A causal LTI system satisfies the linear differential equation

$$\frac{d^2}{dt^2} y(t) + 7 \frac{d}{dt} y(t) + 12 y(t) = \frac{d}{dt} x(t) + 2x(t)$$

(i) Find the frequency response $H(j\Omega)$ of the system. (6)

(ii) Find the output $y(t)$ of the system for the input $x(t) = e^{-2t} u(t)$. (7)

14. (a) Let $X(e^{j\omega})$ be the Fourier transform of the sequence $x[n]$. Determine in terms of $x[n]$ the sequence corresponding to the following transforms using the properties of DTFT. Also prove the properties used.

(i) $X(e^{j(\omega-\omega_0)})$ (3)

(ii) $X^*(e^{-j\omega})$ (3)

(iii) $j \frac{d}{d\omega} X(e^{j\omega})$ (3)

(iv) $\frac{1}{2\pi} X_1(e^{j\omega}) \otimes X_1(e^{j\omega})$ (4)

Or

(b) Derive the z -transform of the following sequence

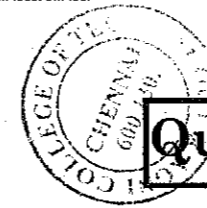
$$x[n] = \sin(\omega_0 n) u[n]$$

Also specify its ROC.



Reg. No. :

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Question Paper Code : 90175

B.E./B.Tech. DEGREE EXAMINATIONS, NOVEMBER/DECEMBER 2019

Third Semester

Electronics and Communication Engineering

EC 8352 – SIGNALS AND SYSTEMS

(Common to Medical Electronics/Biomedical Engineering/Computer and Communication Engineering/Electronics and Telecommunication Engineering)
(Regulations – 2017)

Time : Three Hours

Maximum : 100 Marks

Answer ALL questions

PART – A

(10×2=20 Marks)

1. Determine whether the signal $x(t) = \sin \sqrt{2}t$ is periodic or not.
2. Give an example for deterministic and random signals.
3. State Gibbs Phenomenon.
4. Find the Fourier series coefficients of the signal $x(t) = 1 + \sin \frac{\pi}{2}t$.
5. Two systems with impulse responses $h_1(t) = e^{-at} u(t)$ and $h_2(t) = u(t - 1)$ are connected in parallel. What is the overall impulse response $h(t)$ of the system ?
6. The input – output relationship of a system is given by
$$\frac{d^2y}{dt^2} + 3 \frac{dy}{dt} + 2y = \frac{dx}{dt}$$

Find the system function $H(s)$ of the system.
7. Find the Nyquist rate of the signal $x(t) = \cos 200\pi t + \sin 400\pi t$.
8. Find the z-transform and its associated ROC for the signal
 $x[n] = \delta[n + 1] + 2 \delta [n] - 3 \delta [n - 2]$.
9. Convolve the following signals
 $x[n] = \{1, 2, 3\}$ $h[n] = \{1, 2\}$
10. Determine whether the following system is a recursive system and justify your answer $y[n] = 2x[n] + 3x[n - 1] - 2x[n - 2]$.



PART - B

(5×13=65 Marks)

11. a) Plot the following signals, given $x[n]$:

- i) $x[n] = \{1, 2, 1, 2, 1, 2, 1\}$ (2)
- ii) $x[n-1]$ (2)
- iii) $x[2n]$ (2)
- iv) $x[n/2]$ (2)
- v) $x[\frac{n}{2}-1]$ (2)
- vi) $x[-\frac{n}{2}-1]$ (3)

(OR)

b) Determine whether the following system is Linear, Time Invariant, Causal, Memoryless and Stable.

$$y[n] = nx[n]$$

12. a) Find the Fourier transform of the signal $x(t) = e^{-\alpha|t|}$, $\alpha > 0$ and plot its spectrum.

(OR)

b) Specify all possible ROC's for the function $X(s)$ given below. Also find $x(t)$ in each case.

$$X(s) = \frac{4s}{(s+2)(s+4)}$$

13. a) Convolve the following signals $x(t) = u(t)$ $h(t) = u(t) - u(t-2)$.

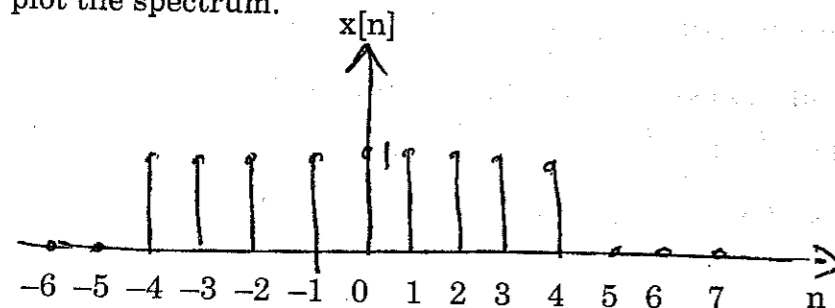
(OR)

b) An LTI system which is initially at rest is described by the differential equation

$$\frac{d^2y}{dt^2} + 3\frac{dy}{dt} + 2y = \frac{dx}{dt} + 3x$$

Find the system function $H(s)$ and the impulse response $h(t)$.

14. a) Find the DTFT of the rectangular pulse sequence shown below and also plot the spectrum.



(OR)



b) Given the z -transform of a sequence $x[n]$ as $X(z) = \frac{z}{z-1}$

Find the z -transform of the following signals in terms of $X(z)$ using properties of z -transform.

- i) $x[n-1]$ (3)
- ii) $x[-n]$ (3)
- iii) $\alpha^n x[n]$ (3)
- iv) $nx[n]$ (4)

15. a) Convolve the following signals $x[n] = \alpha^n u[n]$ $h[n] = u[n-1]$.

(OR)

b) Consider a DT LTI system whose system function $H(z)$ is given by

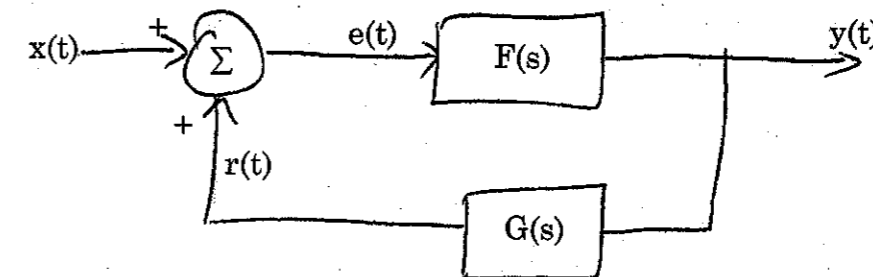
$$H(z) = \frac{z}{z-0.5} \quad |z| > 0.5$$

Find the step response of the system.

PART - C

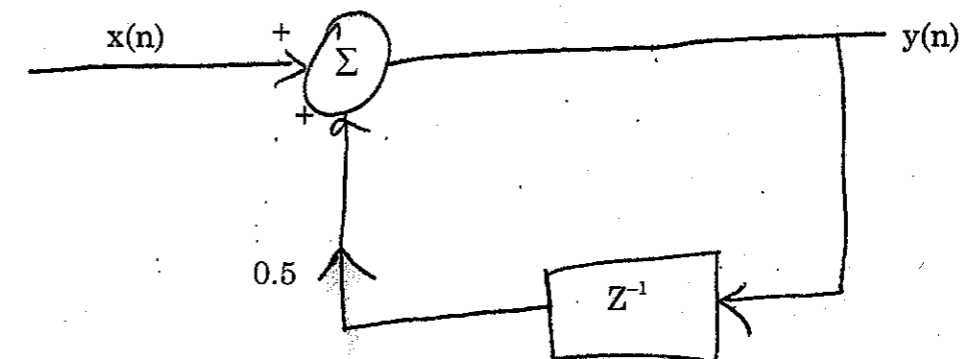
(1×15=15 Marks)

16. a) The feedback interconnection of two causal subsystems with system functions $F(s)$ and $G(s)$ is shown below. Find the overall system function $H(s)$ for this feedback system.



(OR)

b) Consider the discrete time LTI system shown below.



Find the frequency response $H(e^{j\omega})$ and the impulse response $h(n)$ of the system. Sketch the magnitude response $|H(e^{j\omega})|$ for the system.

15. (a) (i) Realise the following system in cascade form (10)

$$H(z) = \frac{1 + \frac{1}{2}z^{-1}}{\left(1 - \frac{1}{2}z^{-1} + \frac{1}{3}z^{-2}\right)\left(1 + \frac{1}{4}z^{-1}\right)}$$

(ii) Convolve $x(n) = \{1, 1, 0, 1, 1\}$ (6)

$$h(n) = \{1, -2, -3, 4\}$$

OR

(b) A system is governed by a linear constant coefficient difference equation
 $y(n] = 0.7y[n-1] - 0.1y[n-2] + 2x[n] - x[n-2]$
 Find the output response of the system $y(n)$ for an input $x(n) = u(n)$ (16)

Reg. No.

Question Paper Code : 57282

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B.E./B.Tech. DEGREE EXAMINATION, MAY/JUNE 2016

Third Semester

Electronics and Communication Engineering

EC 6303 - SIGNALS AND SYSTEMS

(Common to Biomedical Engineering and Medical Electronics Engineering)

(Regulations 2013)

Time : Three Hours

Maximum : 100 Marks

Answer ALL questions.

PART - A (10 × 2 = 20 Marks)

1. Sketch the following signals :
 $\text{rect}\left(\frac{t+1}{4}\right)$; 5 ramp (0,1)
2. Given $g(n) = 2e^{-2n-3}$. Write out and simplify the functions
 (i) $g(2-n)$ (ii) $g\left(\frac{n}{10} + 4\right)$
3. What is the inverse Fourier transform of
 (i) $e^{-32\pi f_0}$ (ii) $\delta(f - f_0)$
4. Give the Laplace Transform of $x(t) = 3e^{-2t}u(t) - 2e^{-t}u(t)$ with ROC.
5. Find whether the following system whose impulse response is given is causal and stable $h(t) = e^{-2t}u(t-1)$.
6. Realize the block diagram representing the system $H(s) = \frac{s}{s+1}$.
7. Write the conditions for existence of DTFT.

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8. Find the final value of the given signal

$$X(z) = \frac{1}{1 + 2z^{-1} + 3z^{-2}}$$

9. From discrete convolution sum, find the step response in terms of $h(n)$.
10. Define the non recursive system.

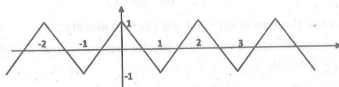
PART - B (5 × 16 = 80 Marks)

11. (a) (i) Find whether the following signals are periodic or aperiodic. If periodic find the fundamental period and fundamental frequency (8)
 $x_1(n) = \sin 2\pi n + \cos \pi n$
 $x_2(n) = \sin \frac{\pi n}{3} \cos \frac{\pi n}{5}$
 (ii) Find whether the following signals are power or energy signals. Determine power and energy of the signals. (8)
 $g(t) = 5 \cos\left(17\pi t + \frac{\pi}{4}\right) + 2 \sin\left(19\pi t + \frac{\pi}{3}\right)$
 $g(n) = (0.5)^n u(n)$

OR

- (b) Find whether the following systems are time variant or fixed. Also find whether the systems are linear or nonlinear (8)
 $\frac{d^3y(t)}{dt^3} + 4 \frac{d^2y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + y(t) = x(t)$
 $y(n) = an^2 \times (n) + bn \times (n-2)$ (8)

12. (a) Obtain the Fourier series coefficients & Plot the spectrum for the given waveform (16)



OR

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- (b) (i) From basic formula, determine the Fourier transform of the given signals. Obtain the magnitude and phase spectra of the given signals. (5 + 5)
 $te^{-at}u(t)$, $a > 0$
 e^{-at} , $a > 0$
- (ii) State and prove Rayleigh's energy theorem. (6)

13. (a) (i) Using graphical convolution, find the response of the system whose impulse response is
 $h(t) = e^{-2t}u(t)$
 for an input $x(t) = \begin{cases} A, & \text{for } 0 \leq t \leq 2 \\ 0, & \text{otherwise} \end{cases}$ (8)

- (ii) Realize the following in indirect form II. (8)
 $\frac{d^3y(t)}{dt^3} + 4 \frac{d^2y(t)}{dt^2} + 7 \frac{dy(t)}{dt} + 8y(t) = 5 \frac{d^2x(t)}{dt^2} + 4 \frac{dx(t)}{dt} + 7x(t)$

OR

- (b) (i) An LTI system is defined by the differential equation (10)
 $\frac{d^2y(t)}{dt^2} - 4 \frac{dy(t)}{dt} + 5y(t) = 5x(t)$

Find the response of the system $y(t)$ for an input $x(t) = u(t)$, if the initial conditions are $y(0) = 1$; $\frac{dy(t)}{dt} \Big|_{t=0} = 2$.

- (ii) Determine frequency response and impulse response for the system described by the following differential equation. Assume zero initial conditions. (6)

$$\frac{dy(t)}{dt} + 3y(t) = x(t)$$

14. (a) (i) State and prove sampling theorem. (10)
- (ii) What is aliasing? Explain the steps to be taken to avoid aliasing. (6)

OR

- (b) State and prove the following theorems : (8)
 (i) Convolution theorem of DTFT (8)
 (ii) Initial value theorem of z-transform (8)

3

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Reg. No. :

Question Paper Code : 71726

B.E./B.Tech. DEGREE EXAMINATION, APRIL/MAY 2017.

Third Semester

Electronics and Communication Engineering

EC 6303 — SIGNALS AND SYSTEMS

(Common to Biomedical Engineering and Medical Electronics Engineering)

(Regulations 2013)

Time : Three hours

Maximum : 100 marks

(Codes/Tables/Charts to be permitted if any, may be indicated)

Answer ALL questions.

PART A — (10 × 2 = 20 marks)

1. Find the summation $x(n) = \sum_{n=-\infty}^{\infty} \delta(n-1) \sin 2n$.
2. Define a linear system.
3. What is the condition for the existence of Fourier series for a signal?
4. State Parseval's theorem for a continuous time aperiodic signal.
5. Give the expression for convolution integral
6. Given $h(t)$, what is the step response of a CT LTI system.
7. What is the z transform of a unit step sequence.
8. Find $x(\infty)$ of the signal for with the z -transform is given by
$$X(z) = \frac{z+1}{3(z-1)(z+0.9)}$$
9. What is the necessary and sufficient condition on impulse response for stability of a casual LTI system?
10. What is the difference between recursive and nonrecursive systems?

PART B — (5 × 13 = 65 marks)

11. (a) (i) Find out whether the following signals are periodic or not. If periodic find the period $x(t) = 2\cos(10t + 1) - \sin(4t - 1)$
 $x(n) = \cos(0.1 \pi n)$.
- (ii) Find out whether the following signals are energy or power signal or neither power nor energy. Determine power or energy as the case may be for the signal $x(t) = u(t) + 5u(t - 1) - 2u(t - 2)$.

Or

- (b) Determine the properties viz linearity, causality, time invariance and dynamicity of the given systems

$$y(t) = \frac{d^2 y}{dt^2} + 3t \frac{dy}{dt} + y(t) = x(t)$$

$$y_1(n) = x(n^2) + x(n)$$

$$y_2(n) = \log_{10} x(n)$$

12. (a) Obtain the Fourier co-efficient and write the quadrature form of a fully rectified sine wave.

Or

- (b) Determine the inverse-Laplace Transform of the following

$$(i) \quad x(s) = \frac{1 - 2s^2 - 14s}{s(s+3)(s+4)}$$

$$(ii) \quad x(s) = \frac{2s^2 + 10s + 7}{(s+1)(s^2 + 3s + 2)}$$

13. (a) A causal LTI system having a frequency response $H(j\Omega) = \frac{1}{j\Omega + 3}$ is producing an output $y(t) = e^{-3t}u(t) - e^{-4t}u(t)$ for a particular input $x(t)$. Determine $x(t)$.

Or

- (b) Realize the given system in parallel form $H(s) = \frac{s(s+2)}{s^3 + 8s^2 + 19s + 12}$

14. (a) State and prove Sampling theorem.

Or

- (b) State and prove the following properties of DTFT

- (i) Differentiation in frequency
 (ii) Convolution in frequency domain.

15. (a) Perform convolution to find the response of the systems $h_1(n)$ and $h_2(n)$ for the input sequences $x_1(n)$ and $x_2(n)$ respectively.

$$(i) \quad x_1(n) = \{1, -1, 2, 3\} \quad h_1(n) = \{1, -2, 3, -1\}$$

$$(ii) \quad x_2(n) = \{1, 2, 3, 2\} \quad h_2(n) = \{1, 2, 2\}$$

Or

- (b) For a causal LTI system the input $x(n)$ and output $y(n)$ are related through a difference equation $y(n) - \frac{1}{6}y(n-1) - \frac{1}{6}y(n-2) = x(n)$. Determine the frequency response $H(e^{j\omega})$ and the impulse response $h(n)$ of the system.

PART C — (1 × 15 = 15 marks)

16. (a) Using Laplace Transform determine the response of the system described by the equation $\frac{d^2 y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 4y(t) = \frac{dx(t)}{dt}$ with initial conditions

$$y(0) = 0; \quad \left. \frac{dy(t)}{dt} \right|_{t=0} = 1 \text{ for the input } x(t) = e^{-2t}u(t).$$

Or

- (b) Determine the steady state response for the system with impulse response $h(n) = [j 0.5]^n$ for an input $x(n) = \cos(\pi n)u(n)$.

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Question Paper Code : 40953

B.E./B.Tech. DEGREE EXAMINATION, APRIL /MAY 2018
Third Semester
Electronics and Communication Engineering
EC 6303 – SIGNALS AND SYSTEMS
(Common to Biomedical Engineering/Medical Electronics)
(Regulations 2013)

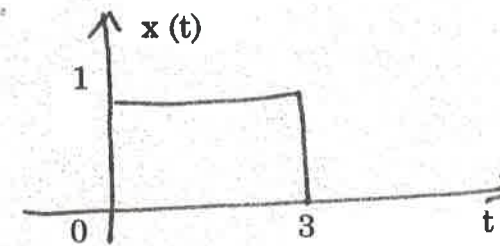
Time : Three Hours

Maximum : 100 Marks

Answer ALL questions

PART – A (10×2=20 Marks)

1. Represent the following signal in terms of the unit step function.



2. What is a random signal ? Give an example.
3. Find the Fourier series representation of the signal $x(t) = \cos \frac{2\pi}{3} t$.
4. Give Parseval's relation for continuous time Fourier transform.
5. Given the input $x(t) = u(t)$ and $h(t) = \delta(t - 1)$. Find the response $y(t)$.
6. Given $X(s) = \frac{3}{s+2}$, ROC : $\text{Re}\{s\} > -2$. Find $x(t)$.
7. Find the Nyquist rate for the signal $x(t) = 1 + \cos 10 \pi t$, in Hz.

8. Find the Inverse DTFT of $X(e^{j\omega}) = 2e^{j\omega} + 1 - 2e^{-2j\omega}$.
9. Draw the block diagram representation of the system given its input output relationship
- $$y[n] = \sum_{k=0}^4 h(k) x[n-k]$$
10. Convolve the following signals
- $x[n] = \{1, 2, -2\}$ and $h[n] = \{1, 2, 2\}$.

PART - B

(5×13=65 Marks)

11. a) i) How the unit impulse function $\delta(t)$, unit step function $u(t)$ and ramp function $r(t)$ can be related? Also give the Mathematical representation and graphical representation of the above three functions. (6)
- ii) Determine whether the following signals is periodic. If a signal is periodic, determine its fundamental period.
- a) $x(t) = \cos \frac{\pi}{3}t + \sin \frac{\pi}{4}t$ (4)
- b) $x[n] = \cos \frac{n}{4}$ (3)

(OR)

- b) Determine whether the system $y[n] = 2x[n-2]$ is memoryless, causal, linear, time invariant, invertible and stable. Justify your answers.
12. a) Find the Fourier series representation for the signal $x(t) = 2 + \cos 4t + \sin 6t$ and plot its magnitude and phase spectrum. (OR)
- b) State and prove any three properties of continuous Time Fourier Transform.
13. a) Given the differential equation representation of a continuous time system.
- $$\frac{d}{dt}y(t) + 2y(t) = x(t)$$
- Find the response $y(t)$ for the input $x(t) = e^{-3t}u(t)$ using Laplace transform. (OR)

- b) A continuous time LTI system is represented by the following differential equation.

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = 2x(t)$$

Determine the impulse response of the system using Fourier transform.

14. a) Find the Z- transform of the sequence $x[n] = a^n u[n] + b^n u[-n-1]$. Considering the two conditions $a > b$ and $a < b$.

(OR)

- b) If $X(e^{j\omega})$ is the DTFT of $x[n]$. Find the DTFT of $(n-1)^2 x[n]$ in terms of $X(e^{j\omega})$ using DTFT properties.
15. a) Convolve the following sequences $x[n] = a^n u[n]$, $a < 1$
- $h[n] = u[n]$

(OR)

- b) The system function $H(z)$ is given by $H(z) = \frac{z^2}{(z-\frac{1}{3})(z-\frac{1}{2})}$ ROC: $|z| > \frac{1}{2}$. Determine the step response of the system.

PART - C

(1×15=15 Marks)

16. a) State and explain sampling theorem with necessary equations and illustrations. (OR)
- b) A discrete time system is both linear and time invariant. The output produced by this system for an impulse input is $\{1, 2, 3\}$. Find the output of this for the following inputs and justify your answer :
- i) $\delta[n-2]$ (5)
- ii) $\delta[n] - 2\delta[n-1]$ (5)
- iii) $\{1, 2, 3\}$. (5)

(3) $x[n] = u(-n)$

(4) $x[n] = a^{-n}u(-n)$

(ii) Verify the convolution property of Z-transform. (5)

15. (a) A causal DT LTI system is described by $y(n) - \frac{3}{4}y(n-1) + \frac{1}{8}y(n-2) = x(n)$. Where $x(n)$ and $y(n)$ are the input and output of the system respectively. (13)

(i) Determine the system function $H(z)$

(ii) Find the impulse response $h(n)$ of the system.

Or

(b) (i) Find the convolution sum of the given sequences using Z-transform $x[n] = [1, 1, 1, 1]$ and $h[n] = [1, 1, 1]$. (6)

(ii) A recursive DT LTI system function $H(z)$ is given by

$$H(z) = \frac{z(3z-4)}{\left(z-\frac{1}{2}\right)(z-3)}. \text{ ROC: } \frac{1}{2} < |z| < 3.$$

Determine whether the system is causal or not. (7)

PART C — (1 × 15 = 15 marks)

16. (a) A unit step input applied to an LTI system at rest results in the response $y(t) = \frac{1}{2}tu(t) - \frac{1}{20}(1 - e^{-10t})u(t)$

Determine the following

(i) Transfer function of the system

(ii) Impulse response of the system

(iii) Response of the system to $x(t) = 2\cos(10t)u(t)$

Use Laplace transform analysis. (15)

Or

(b) Find the output response of a recursive DT system described by the following difference equation $y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = x[n]$, the initial conditions are $y[-1] = 0$, $y[-2] = 1$ and the input $x[n]$ is $x[n] = \left[\frac{1}{2}\right]^n$. Use Z-transform analysis. (15)

Reg. No. :

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Question Paper Code : 52908



B.E./B.Tech. DEGREE EXAMINATIONS, APRIL/MAY 2019.

Third Semester

Electronics and Communication Engineering

EC 6303 — SIGNALS AND SYSTEMS

(Common to : Biomedical Engineering/Medical Electronics)

(Regulation 2013)

(Also common to : PTEC 6303 – Signals and Systems for B.E. (Part-Time) – Second Semester – Electronics and Communication Engineering Regulation 2014)

Time : Three hours

Maximum : 100 marks

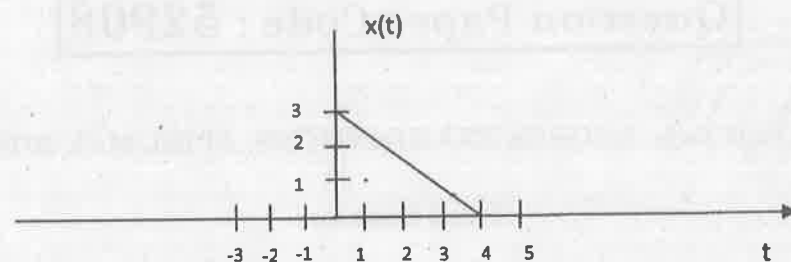
Answer ALL questions.

PART A — (10 × 2 = 20 marks)

1. Sketch the signal $x(t) = \delta(t - t_0)$.
2. Find whether the described as system $y[n] : x = nx[n]$ $y(n) = nx(n)$ is time invariant or not.
3. State the importance of Fourier series.
4. Find Laplace transform for the signal $x(t) = e^{-at}u(t)$, $a > 0$.
5. Find the system function for the given LTI differential equation. $\frac{dy(t)}{dt} + 2y(t) = x(t) + \frac{dx(t)}{dt}$.
6. Show that $x(t) * \delta(t - t_0) = x(t - t_0)$.
7. State the condition for baseband sampling.
8. State the frequency shifting theorem of DTFT.
9. Write down the expression of convolution sum operation of two signals $x_1[n]$ and $x_2[n]$.
10. Define recursive and non recursive system.

PART B — (5 × 13 = 65 marks)

11. (a) (i) A continuous time signal $x(t)$ is shown below. Sketch and label each of the following signals. (8)



- (1) $x(t-2)$
- (2) $x(2t)$
- (3) $x(t/2)$
- (4) $x(-t)$.

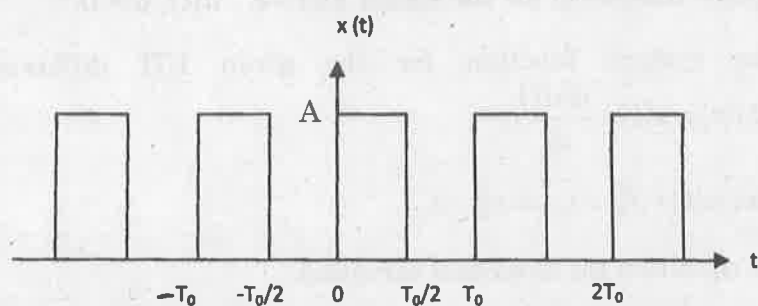
- (ii) Determine whether or not each of the following signal is periodic. If periodic find its fundamental period. (5)

- (1) $x(t) = \sin\left(\frac{2\pi}{3}t\right)$
- (2) $x[n] = \cos\left(\frac{n}{8} - \pi\right)$.

Or

- (b) A system has the input output relation given by $y[n] = x[n] + n x[n+1]$. Determine whether or not the given system is (i) Causal (ii) Static (iii) Time invariant (iv) Linear (v) Stable. (13)

12. (a) Consider the periodic square wave $x(t)$ shown below. (13)



Determine the complex exponential Fourier series of $x(t)$.

Or

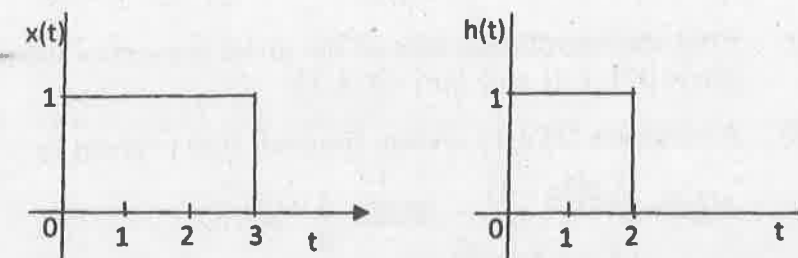
- (b) (i) Find the Fourier transform of the given signal $x(t) = e^{-at}u(-t)$, $a > 0$. (5)

- (ii) Find the inverse Laplace transform of the following $X(s)$. (8)

(1) $X(s) = \frac{s}{s^2 + 4}$, $\text{Re}(s) > 0$

(2) $X(s) = \frac{s+1}{(s+2)^2 + 4}$, $\text{Re}(s) > -1$.

13. (a) Evaluate $y(t) = x(t) * h(t)$, by analytical method where $x(t)$ and $h(t)$ are shown in figure below. (13)



Or

- (b) (i) Consider a continuous time LTI system described by $\frac{dy(t)}{dt} + 2y(t) = x(t)$. Using Fourier transform, find the output $y(t)$ for the given input signal $x(t) = e^{-at}u(t)$. (5)

- (ii) The output $y(t)$ of a continuous time LTI system is found to be $2e^{-3t}u(t)$ when the input $x(t)$ is $u(t)$. Determine the impulse response $h(t)$ of the system. (8)

14. (a) State and prove the following properties of DTFT. (13)

- (i) Linearity.
- (ii) Time shifting.
- (iii) Frequency shifting.
- (iv) Complex Conjugation.
- (v) Time reversal.

Or

- (b) (i) Find the z-transform and associated ROC for each of the following sequences (8)

(1) $x[n] = \delta(n - n_0)$

(2) $x[n] = u(n - n_0)$

Reg. No. :

Question Paper Code : 80334

B.E./B.Tech. DEGREE EXAMINATION, NOVEMBER/DECEMBER 2016.

Third Semester

Electronics and Communication Engineering

EC 6303 – SIGNALS AND SYSTEMS

(Common to Biomedical Engineering and Medical Electronics Engineering)

(Regulations 2013)

Time : Three hours

Maximum : 100 marks

Answer ALL questions.

PART A — (10 × 2 = 20 marks)

1. Give the mathematical and graphical representation of a continuous time and discrete time unit impulse functions.
2. State the difference between causal and non causal system.
3. Find the Fourier series representation of the signal $x(t) = \frac{\cos 2\pi t}{3}$ and determine the Fourier series coefficients.
4. Find the Laplace transform of $x(t) = e^{-at}u(t)$.
5. Convolve the following signals $u(t-1)$ and $\delta(t-1)$.
6. Given $H(s) = \frac{s}{s^2 + 2s + 1}$. Find the differential equation representation of the system.
7. Find the Nyquist rate of the signal $x(t) = \sin 200\pi t - \cos 100\pi t$
8. Find the Z-transform of the signal and its associated ROC $x[n] = \{2, -1, 3, 0, 2\}$.

9. Convolve the following sequences

$$x[n] = \{1, 2, 3\}$$

$$h[n] = \{1, 1, 2\}$$

10. Given the system function $H(z) = 2 + 3z^{-1} + 4z^{-3} - 5z^{-4}$. Determine the impulse response $h[n]$.

PART B — (5 × 13 = 65 marks)

11. (a) Determine whether the system is Linear, Time Invariant, Causal and memoryless $y(t) = \frac{1}{2} \int_{-\infty}^t x(z) dz$.

$$y(t) = \frac{1}{2} \int_{-\infty}^t x(z) dz$$

Or

(b) Sketch the following signals

(i) $u(-t+2)$

(ii) $r(-t+3)$

(iii) $2\delta[n+2] + \delta[n] - 2\delta[n-1] + 3\delta[n-3]$

(iv) $u[n+2]u[-n+3]$

where $u(t)$, $r(t)$, $\delta[n]$, $u[n]$ represent continuous time unit step, continuous time ramp, discrete time impulse and discrete time step functions respectively.

12. (a) Find the Fourier transform of the signal $x(t) = \cos \Omega_0 t u(t)$.

Or

(b) State and prove the multiplication and convolution property of Fourier transform.

13. (a) Convolve the following signals

$$x(t) = e^{-3t}u(t)$$

$$h(t) = u(t+3)$$

Or

(b) A system is described by the differential equation $\frac{d^2}{dt^2}y(t) + 6\frac{d}{dt}y(t) + 8y(t) = \frac{d}{dt}x(t) + x(t)$. Find the transfer function and the output signal $y(t)$ for $x(t) = \delta(t)$.

14. (a) (i) Discuss the effects of undersampling a signal using necessary diagrams. (5)

(ii) Find the Z-transform of $x[n] = a^n u[n] - b^n u[-n-1]$ and specify its ROC. (8)

Or

(b) (i) Give the relation between Discrete Time Fourier Transform (DTFT) and Z-transform. (5)

(ii) State and prove the time shifting property and time reversal property of Z-transform. (8)

15. (a) Convolve the following signals

$$x[n] = u[n] - u[n-3]$$

$$h[n] = (0.5)^n u[n]$$

Or

(b) Determine whether the given system is stable by finding $H(z)$ and plotting the pole-zero diagram

$$y[n] = 2y[n-1] - 0.8y[n-2] + x[n] + 0.8x[n-1]$$

PART C — (1 × 15 = 15 marks)

16. (a) A causal system has input $x[n]$ and output $y[n]$. Find the

(i) System function $H(z)$. (4)

(ii) Impulse Response $h[n]$. (6)

(iii) Frequency response $H(e^{j\omega})$. (5)

$$x[n] = \delta[n] + \frac{1}{6}\delta[n-1] - \frac{1}{6}\delta[n-2]$$

$$h[n] = \delta[n]^6 - \frac{2}{3}\delta[n-1]$$

Or

(b) Find the response $y(t)$ of a continuous time system using Laplace transform with transfer function $H(s) = \frac{1}{(s+2)(s+3)}$ for an input $x(t) = e^{-t}u(t)$.



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Question Paper Code : 50435

02/11/17
F2

B.E./B.Tech. DEGREE EXAMINATION, NOVEMBER/DECEMBER 2017

Third Semester

Electronics and Communication Engineering

EC6303 – SIGNALS AND SYSTEMS

(Common to : Medical Electronics , Biomedical Engineering)

(Regulations 2013)

Time : Three Hours

Maximum : 100 Marks

Answer ALL questions.

PART – A

(10×2=20 Marks)

15. a) i) Obtain the parallel realization of the system given by
 $y(n) - 3y(n - 1) + 2y(n - 2) = x(n)$. (6)

ii) Determine the direct form II structure for the system given by difference equation
 $y(n) = \left(\frac{1}{2}\right)y(n - 1) - \left(\frac{1}{4}\right)y(n - 2) + x(n) + x(n - 1)$. (7)

(OR)

b) Using the properties of inverse Z-transform solve : (5+5+3)

i) $X(z) = \log(1 + az^{-1}); |z| > |a|$ and $X(z) = \frac{az^{-1}}{(1 - az^{-1})^2}; |z| > |a|$

ii) Check whether the system function is causal or not

$$H(z) = \frac{1}{1 - (1/2)z^{-1}} + \frac{1}{1 - 2z^{-1}}; |z| > 2$$

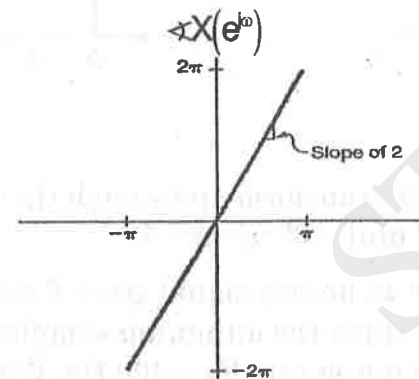
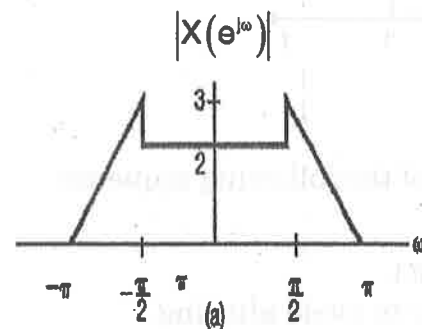
iii) Consider a system with impulse response $H(s) = \frac{e^s}{s+1}; \text{Re}\{s\} > -1$. Check

whether the system function is causal or not.

PART – C

(1×15=15 Marks)

16. a) i) Consider the sequence $x[n]$ whose Fourier transform $X(e^{j\omega})$ is depicted for
 $-\pi \leq \omega \leq \pi$ in the figure below. Determine whether or not, in the time domain,
 $x[n]$ is periodic, real, even, and/or of finite energy. (6)



ii) What is the transfer function and the impulse response of low pass RC circuit? (5)

iii) Find the necessary and sufficient condition on the impulse response $h[n]$
 such that for any input $x[n]$,

$$\max\{|x[n]|\} \geq \max\{|y[n]|\},$$

where $y[n] = x[n] * h[n]$. (4)

(OR)

b) Analyze on recursive and non-recursive systems with an example. (15)

1. Determine if the signal $x[n]$ given below is periodic. If yes, give its fundamental period. If not, state why it is aperiodic.

$$X[n] = \sin\left(\frac{6\pi}{7}n + 1\right)$$

2. Check whether the following system is Time Invariant/Time variant and also causal/non causal : $Y(t) = x\left(\frac{t}{3}\right)$.

3. Find whether the following system with impulse response $h(t)$ are stable or not.
 $h(t) = t e^{-t} u(t)$.

4. Find the Fourier transform of $x(t) = e^{-at} u(t)$.

5. Will there be two different signals having same Laplace transform? Give an example. How do you differentiate these two signals?

6. Consider an LTI system with transfer function $H(s)$ is given by $H(s) = \frac{1}{(s+1)(s+3)}$
 $\text{Re}(s) > 3$; determine $h(t)$.

7. List the ROC properties of Laplace transform.

8. Find the Z transform of a sequence $x[n] = \cos(n\omega T) u[n]$.

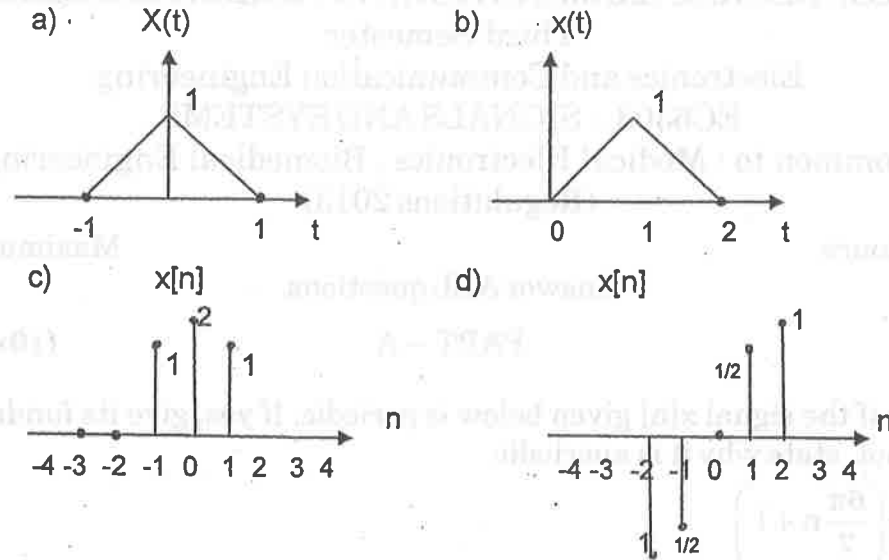
9. Write the condition for stability of a DT-LTI system with respect to the position of poles.

10. Realize the difference equation $y[n] = x[n] - 3x[n - 1]$ in direct form I.

PART – B

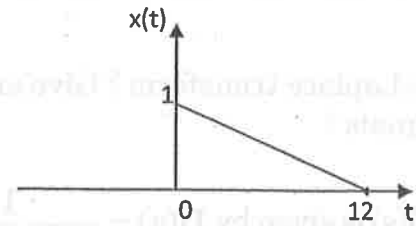
(5×13=65 Marks)

11. a) Find the whether the signal is an energy signal or power signal.
 i) $x(t) = e^{-2t} u(t)$. (5)
 ii) Draw the waveform for the signal $x(t) = r(t) - 2r(t - 1) + r(t - 2)$. (4)
 iii) For the given signal determine whether it is even, odd, or neither. (4)

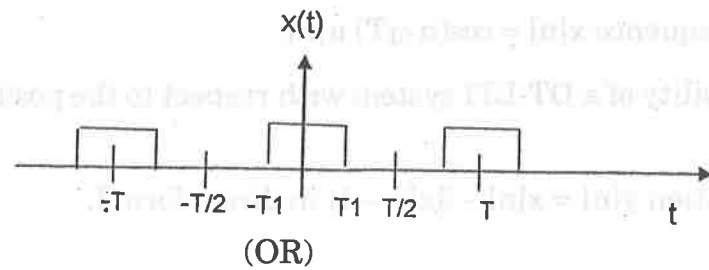


(OR)

- b) Determine whether the following system is Linear and Causal.
 i) $y[n] = x[n]$, $x[n - 1]$ and $y[n] = \left(\frac{1}{3}\right) [x[n - 1] + x[n] + x[n + 1]]$. (5)
 ii) For $x(t)$ indicate in figure sketch the following: (4+4)
 a) $x(1 - t) [u(t + 1) - u(t - 2)]$
 b) $x(1 - t) [u(t + 1) - u(2 - 3t)]$.



12. a) i) Find the Fourier transform of a rectangular pulse with width T and amplitude A. (7)
 ii) Determine the Fourier series coefficients of the following signal. (6)

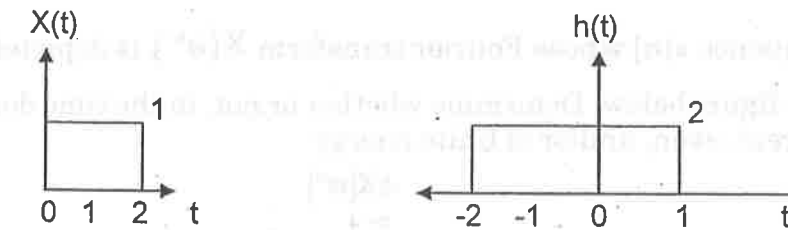


(OR)

- b) i) Determine the Fourier transform for double exponential pulse whose function is given by $x(t) = e^{-a|t|}$, $a > 0$. Also draw its amplitude and phase spectra. (7)
 ii) Obtain the inverse Laplace transform of the function (6)
 $X(s) = \frac{1}{s^2 + 3s + 2}$, ROC: $-2 < \text{Re}\{s\} < -1$.

13. a) i) Using Laplace transform of $x(t)$. Give the pole-zero plot and find ROC of the signal $x(t) = e^{-b|t|}$ for both $b > 0$ and $b < 0$. (6)
 ii) Find the condition for which Fourier transform exists for $x(t)$. Find the Laplace transform of $x(t)$ and its ROC. $x(t) = e^{-at} u(-t)$. (7)
 (OR)

- b) i) Using graphical method, find the output sequence $y[n]$ of the LTI system whose response $h[n]$ is given and input $x[n]$ is given as follows. (6)
 $x[n] = \{0.5, 2\}$; $h[n] = \{1, 1, 1\}$.
 ii) Find the response $y(t)$ of an LTI system whose $x(t)$ and $h(t)$ are shown in fig. (Using convolution integral). (7)



14. a) i) Find the Z transform and sketch the ROC of the following sequence (7)
 $x[n] = 2^n u[n] + 3^n u[-n - 1]$.
 ii) Consider an analog signal $x(t) = 5 \cos 200 \pi t$.
 a) Determine the minimum sampling rate to avoid aliasing.
 b) If sampling rate $F_s = 400$ Hz. What is the DT signal after sampling? (6)

(OR)

- b) i) Determine unit step response of the LTI system defined by (7)
 $d^2y/dt^2 + 5dy/dt + 6y(t) = dx/dt + x(t)$.
 ii) Find the Inverse z-transform using partial fraction method. (6)

$$X(z) = \frac{3 - (5/6)z^{-1}}{(1 - (1/4)z^{-1})(1 - (1/3)z^{-1})} \quad ; |z| > 1/3$$

Reg. No. :

Question Paper Code : 20409

B.E./B.Tech. DEGREE EXAMINATION, NOVEMBER/DECEMBER 2018.

Third Semester

Electronics and Communication Engineering

EC 6303 — SIGNALS AND SYSTEMS

(Common to Biomedical Engineering/Medical Electronics)

(Regulations 2013)

(Also Common to PTEC 6303 – Signals and Systems for B.E. (Part-Time) Second Semester Electronics and Communication Engineering Regulations –2014)

Time : Three hours

Maximum : 100 marks

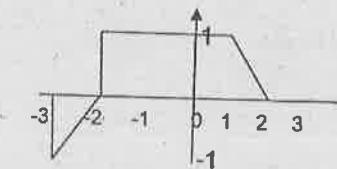
Answer ALL questions.

PART A — (10 × 2 = 20 marks)

1. Compute the average power and energy of the signal $x(t) = r(t) - r(t-2)$, where

$$x(t) = \begin{cases} t; & t \leq 2 \\ 2; & t > 2 \end{cases}$$

2. Plot $x(3-5t)$ for the signal $x(t)$. (Give the sequence of transformation).



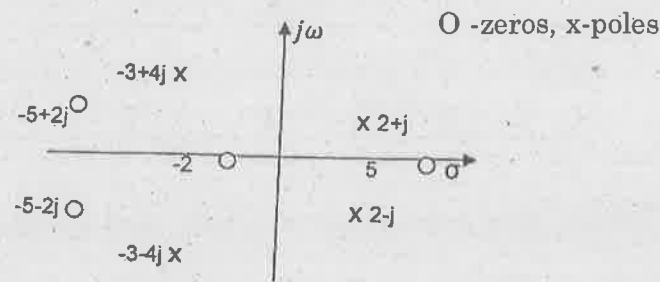
3. Consider a periodic signal $x(t)$ with fundamental frequency 2π and $a_0 = 1$, $a_1 = a_{-1} = 1/4$, $a_2 = a_{-2} = 1/2$, $a_3 = a_{-3} = 1/3$. Express $x(t)$ in general Fourier series formula.

4. State Dirichlet's condition of Fourier transform.

5. The impulse response $h[n]$ is given below. Check the system is stable/causal.

$$h[n] = \left[\frac{1}{3} \right]^n u[n].$$

6. The pole zero plot of the transfer function H(s) of a LTI system is given below.



Plot the ROC for the following cases when:

- (a) The system is causal
- (b) The system is stable.

7. Find the Z-transform of the signal $x[n] = \cos(n\omega T)u[n]$.

8. Find DTFT of the signal $x[n] = \left[\frac{1}{3}\right]^n u[n]$.

9. Find $x(\infty)$ if $X(z)$ is given by $\frac{z+1}{3(z-1)(z+0.9)}$.

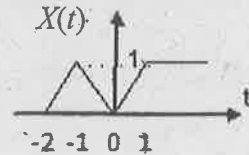
10. Consider the second order system function $H(z) = \frac{1}{\left(1 + \frac{1}{2}Z^{-1}\right)\left(1 - \frac{1}{4}Z^{-1}\right)}$

implement the system in parallel form.

PART B — (5 × 13 = 65 marks)

11. (a) (i) Draw the waveform for the signal $x(t) = u(t) + r(t) - 2r(t-1) + r(t-2) - u(t-2)$, where $u(t)$ and $r(t)$ are unit step and ramp respectively. (3)

(ii) Determine and sketch the even and odd part of the signal. (3)



(iii) A continuous time system is given by $y(t) = \int_{-\infty}^{2t} x(t) dt$. Check whether the system is Linear / Time variant / Causal / Static. (7)

Or

(b) (i) A continuous time system is given by, $y(t) = \begin{cases} 0 & ; x(t) \geq 0 \\ x(t) + x(t-2) & ; x(t) < 0 \end{cases}$

Check whether the system is Linear / Time variant / Causal / Static. (7)

(ii) Draw the waveform for the signal $x(t) = r(t) - 2r(t-1) + r(t-2)$. (3)

(iii) Find whether the signal is periodic or not. (3)

$$x[n] = e^{j\left[\frac{2\pi}{3}\right]n} + e^{j\left[\frac{3\pi}{4}\right]n}$$

12. (a) (i) Find Fourier transform of the signal $x(t) = \begin{cases} 1 & ; |t| < T_1 \\ 0 & ; |t| > T_1 \end{cases}$. (5)

(ii) Find the Laplace transform of the signal $x(t) = e^{-2t}u(t) + e^{-t}(\cos 3t)u(t)$. (8)

Or

(b) (i) Using properties of Fourier transform find $X(j\omega)$ and $G(j\omega)$.

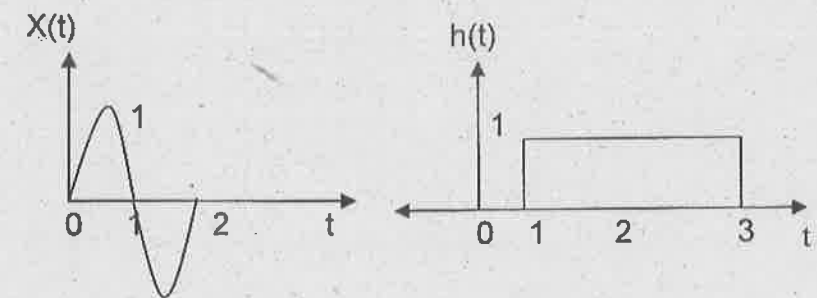
(1) $x(t) = e^{-a|t|} u(t); a > 0$ (3)

(2) $g(t) = 2/(1+t^2)$. (3)

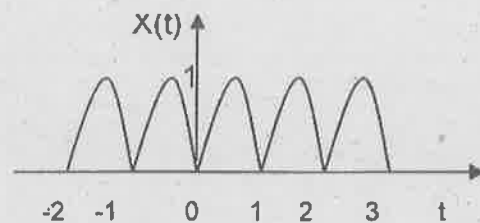
(ii) Find the Inverse Laplace transform of $X(s)$ (7)

$$X(s) = \frac{3s^2 + 8s + 6}{(s+2)(s^2 + 2s + 1)}$$

13. (a) (i) Find the convolution for the given signals. (7)

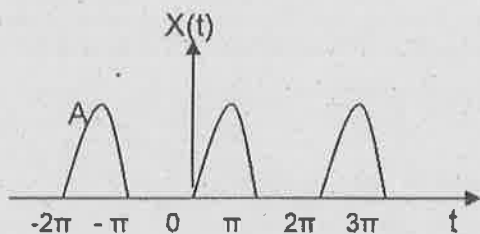


- (ii) Determine the exponential Fourier series representation for the full wave rectified sine wave shown in the figure and also plot the line spectrum. (6)



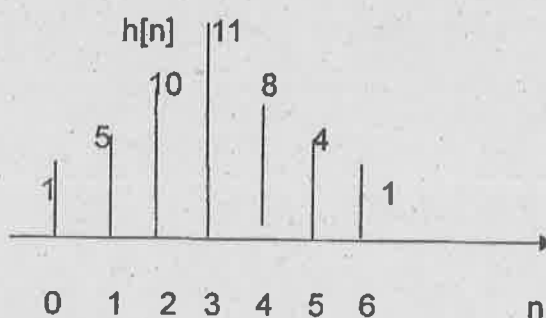
Or

- (b) (i) Find cosine Fourier series of half wave rectified sine function. (8)



- (ii) Find the convolution between $x[n]$ and $h[n]$, where $x[n] = a^n u[n]$; $0 < a < 1$ and $h[n] = u[n]$. (5)

14. (a) (i) Consider the cascade interconnection of 3 causal LTI system. The impulse response $h_2[n] = u[n] - u[n-2]$. The overall response is given below. $X[n] \rightarrow h_1[n] \rightarrow h_2[n] \rightarrow h_2[n] \rightarrow y[n]$.



Find the

- (1) impulse response $h_1[n]$ (4)
 (2) The response of the overall system to the input $x[n] = \delta[n] - \delta[n-1]$. (4)

- (ii) Let $h(t)$ be a triangular pulse and let $x(t)$ be the impulse train. Determine and sketch $y(t)$ for the following value of T .

- (1) $T = 4$
 (2) $T = 2$
 (3) $T = 1$
 (4) $T = 3/2$. (5)

Or

- (b) (i) Using partial fraction method, find the inverse of Z-transform

$$X(z) = \frac{z^2}{(1-az)(z-a)}; \text{Roc: } a < |z| < \frac{1}{a}. \quad (7)$$

- (ii) Find the discrete time Fourier transform $x(n) = (0.5)^n u(n) + 2^n u(-n-1)$. (3)

- (iii) Find the frequency response of the causal system. (3)

$$y[n] - \left(\frac{1}{4}\right)y[n-1] - \left(\frac{3}{8}\right)y[n-2] = x[n] + x[n-1]$$

15. (a) (i) Consider a continuous time LTI system,

$$\frac{d^2 y(t)}{dt^2} - \frac{dy(t)}{dt} - 2y(t) = x(t)$$

- (1) Find the system function $H(s)$. (3)
 (2) Determine the impulse response $h(t)$ for
 (A) the system is causal
 (B) system is stable
 (C) system is neither causal or stable.

- (ii) Realize the given system in direct form II

$$\frac{d^3 y(t)}{dt^3} + 4 \frac{d^2 y(t)}{dt^2} + 7 \frac{dy(t)}{dt} + 8y(t) = 5 \frac{d^2 x(t)}{dt^2} + 4 \frac{dx(t)}{dt} + 7x(t). \quad (7)$$

Or

(b) (i) Consider the system $H(z) = \frac{0.2z}{(z+0.4)(z-0.2)}$; $ROC; |z| > 0.4$. (8)

- (1) Find the impulse response function of the system
- (2) Is DTFT exists for the system? if so, how?
- (3) Find the DTFT.

- (ii) Obtain the cascade form realization of the system described by the difference equation.

$$y(n) - \frac{1}{4}y(n-1) - \frac{1}{8}y(n-2) = x(n) + 3x(n-1) + 2x(n-2). \quad (5)$$

PART C — (1 × 15 = 15 marks)

16. (a) State and prove the properties of discrete Fourier transform. (15)

Or

- (b) Explain the following :

- (i) Deterministic and random signals. (8)
- (ii) Base band sampling. (7)



Reg. No. :

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8/11/19 / AN



Question Paper Code : 91443

B.E./B.Tech. DEGREE EXAMINATIONS, NOVEMBER/DECEMBER 2019

Third Semester

Electronics and Communication Engineering

EC 6303 – SIGNALS AND SYSTEMS

(Common to Biomedical Engineering/Medical Electronics)

(Regulations 2013)

(Also common to : PTEC 6303 – Signals and Systems for B.E. (Part-Time) –

Second Semester – Electronics and Communication Engineering –

Regulations 2014)

Time : Three Hours

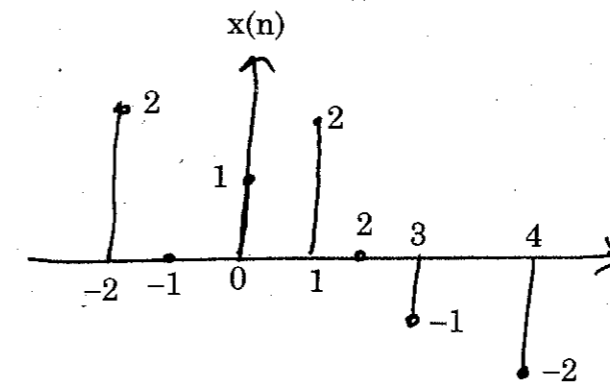
Maximum : 100 Marks

Answer ALL questions

PART – A

(10×2=20 Marks)

1. The graphical representation of a signal $x(n]$ is given below



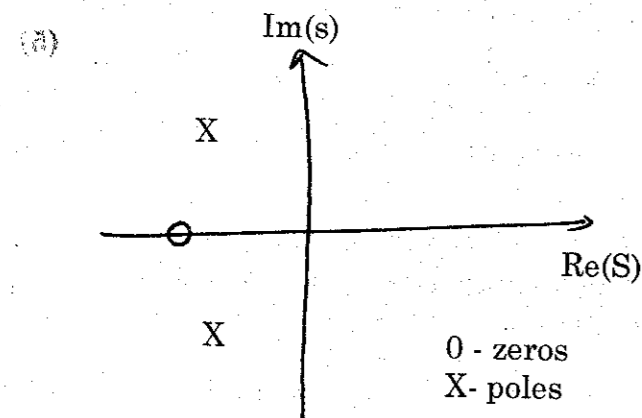
Represent $x(n]$ in terms of impulse functions.

2. Determine whether the following signal $x(t) = e^{-at} u(t)$, $a > 0$ is an energy signal or power signal.

3. Given the Fourier series coefficients of a signal $x(t)$, $a_1 = a_{-1} = \frac{1}{2}$ and the

fundamental frequency of the signal is $\Omega_0 = \frac{2\pi}{3}$. Determine the signal $x(t)$.

4. State initial value theorem of Laplace transform.
5. Given the pole zero diagram of a continuous time system. Determine whether the system is causal and stable.



6. Given the differential equation representation of a continuous time system $2\frac{d^2y(t)}{dt^2} - 3\frac{dy(t)}{dt} + y(t) = 3x(t)$. Find the frequency response $H(j\Omega)$.
7. Find the Nyquist rate for the signal $x(t) = 1 + \cos 200\pi t + \sin 500\pi t$.
8. Find the z-transform of the sequence $x[n] = 2\delta(n+2) + 2\delta(n) - 3\delta(n-1) + 4\delta(n-3)$. Also specify its ROC.
9. If the input $x(n)$ has non-zero samples in the range $N_1 \leq n \leq N_2$ and the impulse response $h(n)$ has a range $N_3 \leq n \leq N_4$. What is the range of the output response $y(n)$ of an LTI system?
10. If the frequency response $H(e^{j\omega})$ of a system is given by

$H(e^{j\omega}) = 2e^{2j\omega} + 3e^{j\omega} + 4 + 2e^{-j\omega} + 3e^{-3j\omega}$. Determine the impulse response $h(n)$ of the system.

PART - B

(5×13=65 Marks)

11. a) i) Plot the signal, $x(t) = 2u(t) - u(t-3)$. (3)
 ii) With relevant examples, explain how the continuous time signals are classified based on their properties. (10)
 (OR)
 b) i) Consider an LTI system with input $x_1(t)$ and output $y_1(t)$. Determine and sketch the response of the system for the input $x_2(t)$ shown in Figure 1. (5)

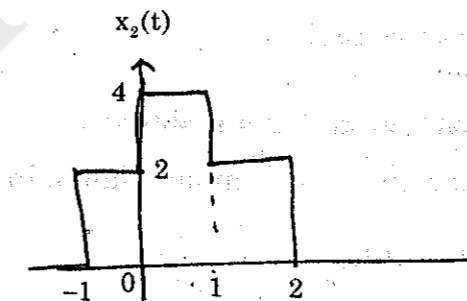
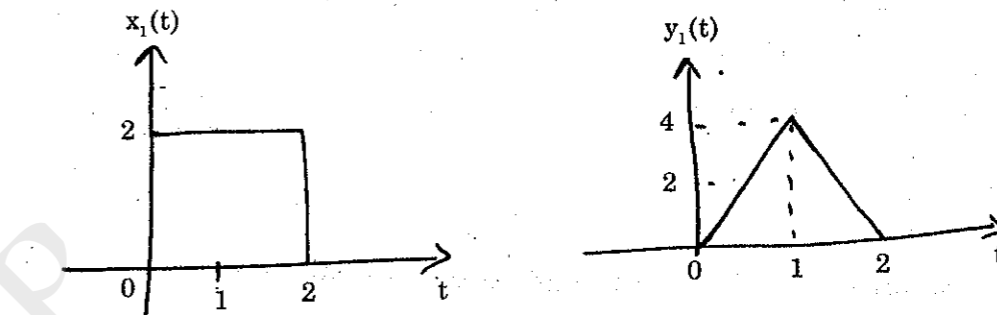


Figure 1

- ii) Determine whether the system $y(n) = 2x[n+1] + 3$ is causal, memoryless, linear and time invariant. (8)
12. a) i) The spectrum $X(j\Omega)$ of a signal $x(t)$ is shown in Figure 2. Determine the equivalent time domain signal $x(t)$ and plot. (7)

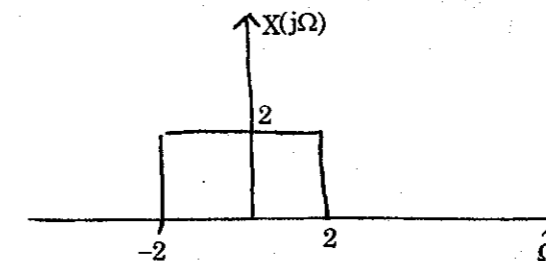


Figure 2

- ii) Find the Laplace transform of $x(t) = e^{-2t}u(t) - e^{2t}u(-t)$ and specify its ROC. (6)
 (OR)



b) i) Find the Fourier transform of the periodic signal $x(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_s)$. (7)

ii) Find the inverse Laplace transform of $X(s) = \frac{2s+1}{s+3}$ ROC : $\text{Re}\{s\} > -3$. (6)

13. a) Compute the response of the system with impulse response $h(t) = u(t+2)$ for the input $x(t) = e^{-2t}u(t)$. (13)

(OR)

b) The transfer function of a continuous time LTI system is given by

$$H(s) = \frac{2}{s^2 + 3s + 2}$$

i) Determine the impulse response of the system. (4)

ii) Find the differential equation representing the input-output relationship. (5)

iii) Plot the pole zero diagram and assess its stability. (4)

14. a) The continuous time signal $x(t) = 2 \cos 150 \pi t + 2 \sin 400 \pi t$ is sampled, using $\Omega_s = 200 \pi$ rad/sec. Sketch the spectrum of the sampled signal. Indicate whether aliasing occurs or not. (13)

(OR)

b) i) State and prove Parseval's relation for discrete aperiodic signal. (6)

ii) Find the z-transform of $x(n) = \left(\frac{1}{3}\right)^{n+1} u(n+2)$ and also specify its ROC. (7)

15. a) Given $x(n) = (0.25)^n u(n)$ and $h(n) = \left\{ -2\left(\frac{1}{3}\right)^n + 3\left(\frac{1}{2}\right)^n \right\} u(n)$. Determine the response, $y(n)$ of the system. (13)

(OR)

b) Given the difference equation representation of a system

$$y(n) - \frac{5}{6}y(n-1) + \frac{1}{6}y(n-2) = x(n)$$

Find the Frequency response $H(e^{j\omega})$ and the impulse response $h(n)$ of the system. (13)



PART - C

(1×15=15 Marks)

16. a) A system is characterized by the difference equation $y(n) = -0.2y(n-1) + 0.4y(n-2) + x(n) - 0.25x(n-1) + 0.5x(n-2)$. Draw the direct form - I, direct form - II, cascade and parallel realization structures. (15)

(OR)

b) Find the Fourier series coefficients of the signal given in Figure 3.

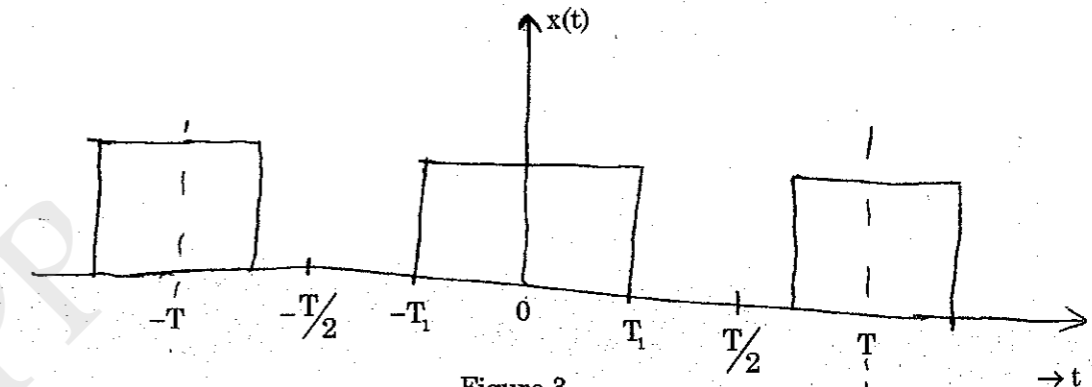


Figure 3

Also plot the spectrum of the signal.

(15)